AP Physics 1 - Test 09 - Rotational Dynamics

Score:

- One revolution is the same as
- 57 rad
- pi/2 rad
- pi rad
- 2*pi rad
 - One revolution per minute is about
- 0.0524 rad/s

0.105 rad/s

0.95 rad/s

1 min = 60 sec

1.57 rad/s

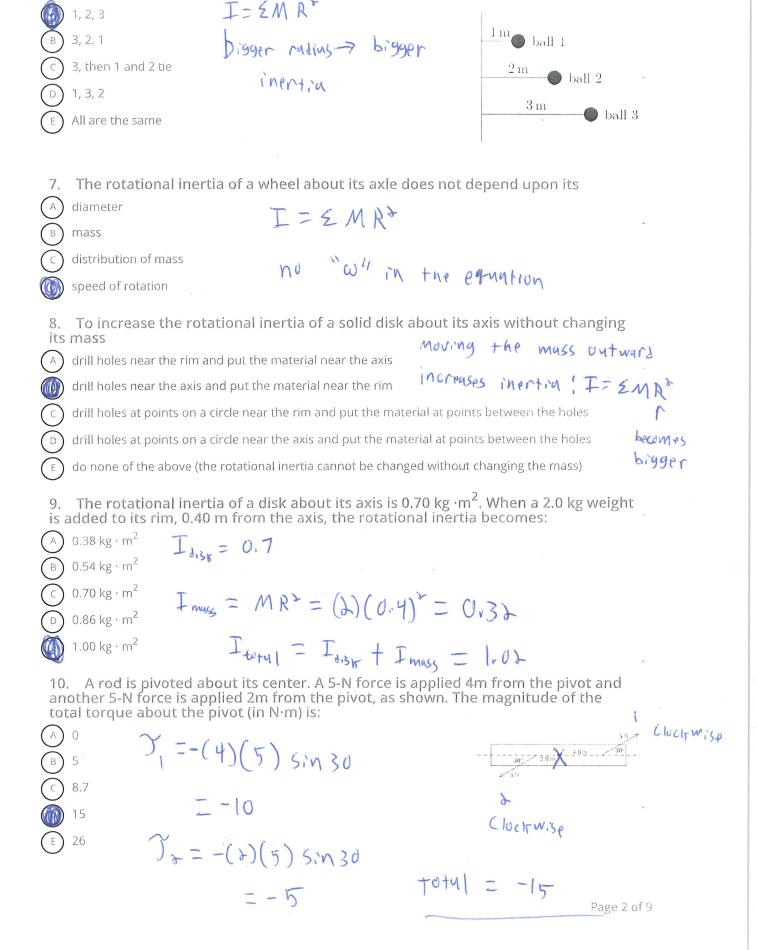
6.28 rad/s

- If a wheel turns with constant angular speed then
- each point on its rim moves with constant velocity
- each point on its rim moves with constant acceleration В
- the wheel turns through equal angles in equal times
- the angle through which the wheel turns in each second increases as time goes on
- the angle through which the wheel turns in each second decreases as time goes on
- The angular speed of the second hand of a watch is
- $(\pi/1800) \text{ rad/s}$

my KP

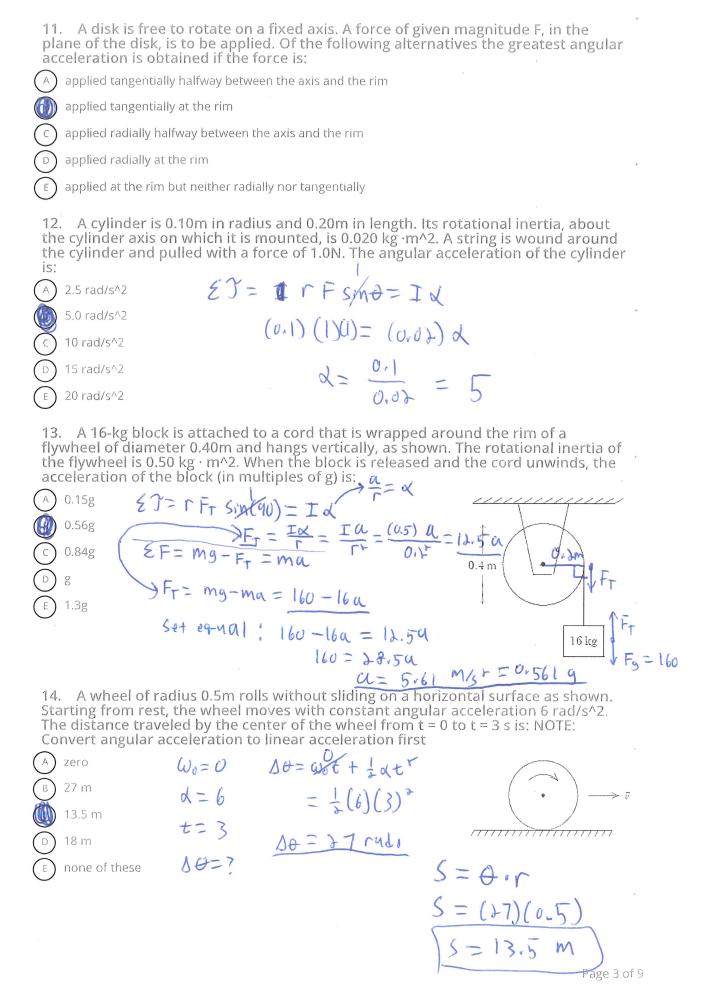
- $(\pi/60)$ rad/s
- $(\pi/30)$ rad/s
- (2π) rad/s (60) rad/s

- Ten seconds after an electric fan is turned on, the fan rotates at 300 rev/min. Its average angular acceleration is >x == 31.4 rud
- 3.14 rad/s^2
- 30 rad/s^2
- 30 rev/s^2
- 50 rev/min^2
- 1800 rev/s^2

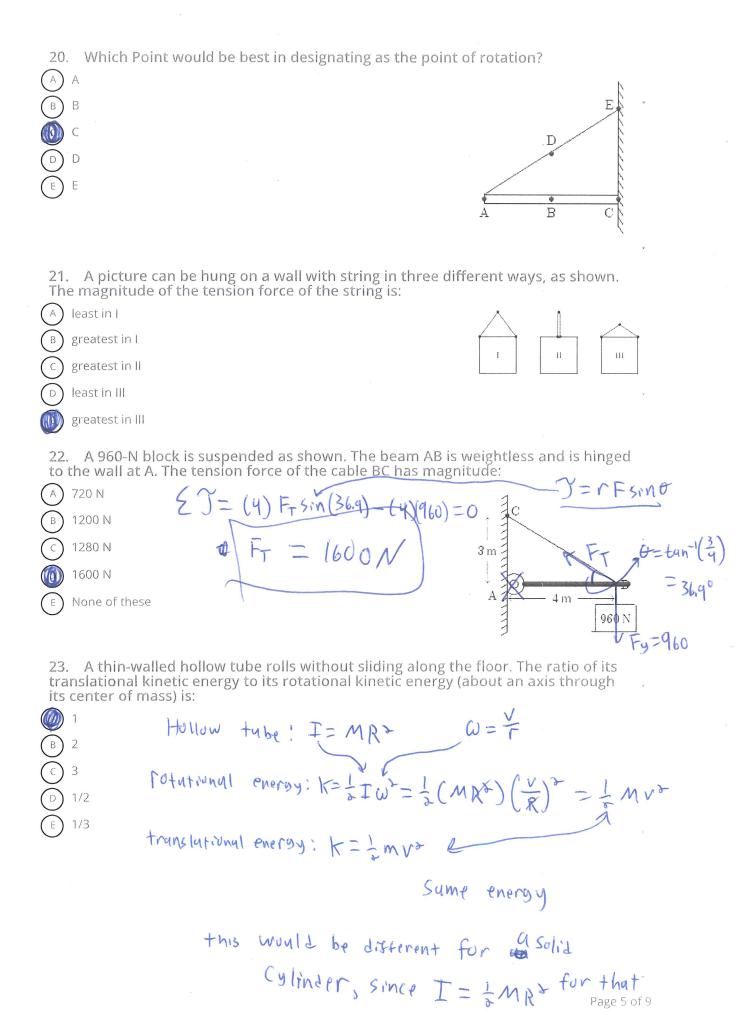


6. Three identical balls are tied by light strings to the same rod and rotate around it, as shown above. Rank the balls according to their rotational inertia, least to

greatest.



| 15 (A) | . A net torque applied to a rigid object always tends to produce | | | | |
|-----------------|---|--|--|--|--|
| B | rotational equilibrium just like a not Fince | | | | |
| | angular acceleration | | | | |
| | rotational equilibrium just like a net Furce angular acceleration malres Sumething accelerate | | | | |
| E | none of these | | | | |
| | | | | | |
| 16 | | | | | |
| | hold for every body in static equilibrium | | | | |
| (B) | | | | | |
| \bigcirc | hold for every body | | | | |
| | are always sufficient to calculate the forces on a solid object in equilibrium | | | | |
| | are sufficient to calculate the forces on a solid object in equilibrium only if the object is elastic | | | | |
| 17 | . For a body to be in equilibrium under the combined action of several forces: | | | | |
| \bigcirc | all the forces must be applied at the same point | | | | |
| B | all of the forces form pairs of equal and opposite forces | | | | |
| | the sum of the components of all the forces in any direction must equal zero | | | | |
| | any two of these forces must be balanced by a third force | | | | |
| \bigcirc | the lines of action of all the forces must pass through the center of gravity of the body | | | | |
| 18 | . For a body to be in equilibrium under the combined action of several forces | | | | |
| \bigcirc A | all the forces must be applied at the same point | | | | |
| (B) | all of the forces form pairs of equal and opposite forces | | | | |
| $($ $^{\circ})$ | any two of these forces must be balanced by a third force | | | | |
| | the sum of the torques about any point must equal zero | | | | |
| E | the lines of action of all the forces must pass through the center of gravity of the body | | | | |
| 19 pe sta | Three identical uniform rods are each acted on by two or more forces, all rependicular to the rods and all equal in magnitude. Which of the rods could be in atic equilibrium if an additional force is applied at the center of mass of the rod? | | | | |
| \bigcirc | Only 1 | | | | |
| В | Only 2 | | | | |
| | Only 3 | | | | |
| | Only 1 and 2 | | | | |
| E | All three | | | | |

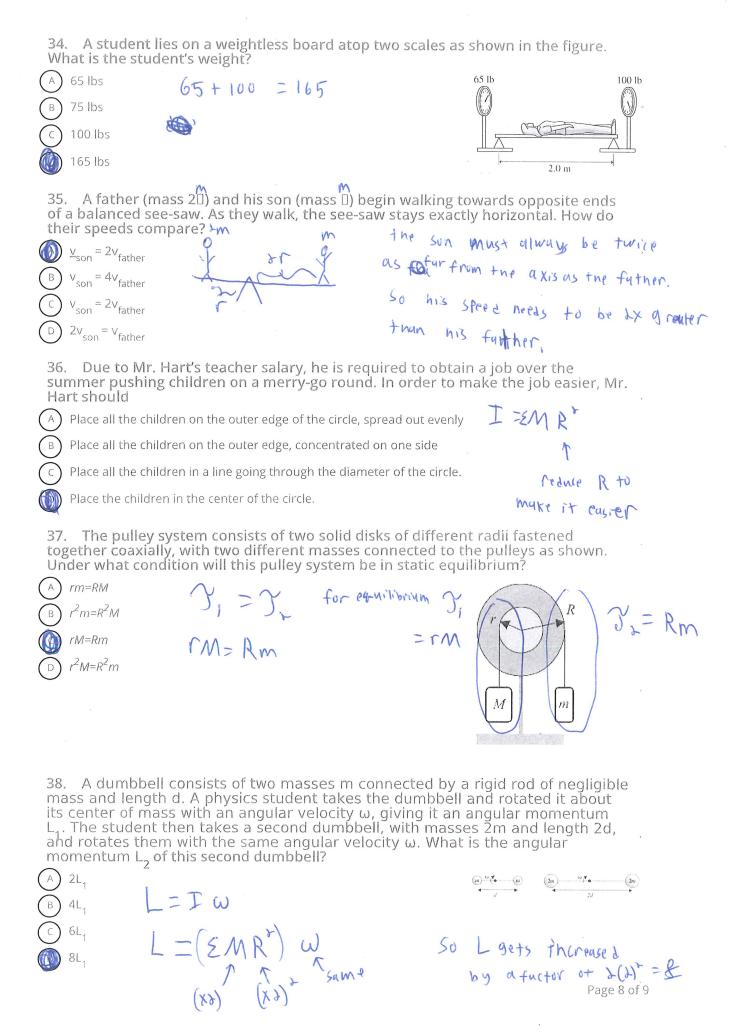


| 24. A sphere and a c from rest on the same Then: | ylinder of equal mass e inclined plane and r | and radius are oll without slidi | simultane ng down th | ously released ne incline. | |
|---|--|--|-------------------------|-------------------------------|-----------|
| A the sphere reaches the | e bottom first because it ha | s the greater inerti | а | | |
| B the cylinder reaches th | ne bottom first because it p | icks up more rotati | onal energy | | ¥ |
| c the sphere reaches the | e bottom first because it pic | cks up more rotatio | nal energy | | |
| D they reach the bottom | together | | | | |
| none of the above are | true | | | | |
| outer radius, start wit Rank the objects acco | ording to how high the | d roll without sl y go, least to gr | iding up id eatest. | entical inclines | • |
| (A) hoop, disk, sphere | I have = MR+ > | must inertion | l | 11-270 | |
| B disk, hoop, sphere | I hoop = MR > > | so must en | 1 proy > | arautar C | i |
| c sphere, hoop, disk | Idisk = IMR | | | hoight | (|
| aphara disk hoon | - | | | | |
| (E) hoop, sphere, disk | Isthere = 2 MR | - > least iner | Mrg -> least | Pherau > Sm | callect b |
| rotational kinetic energy A half its translational kin the same as its translational kin C twice its translational kin D four times its translational kinetic translational | netic energy tional kinetic energy kinetic energy onal kinetic energy | Look at | # } | } | × |
| 27. The fundamenta | ıl dimensions of angul | ar momentum | are: | | |
| A mass·length·time^-1 | 1 | | | | |
| B mass·length^-2·time^- | $L = I \omega$ | F | | | |
| c mass^2·time^-1 | har Ma- | nad. | to me | | |
| D mass-length^2-time^-2 | <u>k</u> g | 5 | (1 d. w) | | * |
| none of these | | | 5 | | |
| 28. Possible units of | angular momentum a | are: | | | |
| (A) kg·m/s | | | | | |
| B kg·m2/s2 | | | | | |
| (c) kg·m/s2 | | | | | è |
| kg·m2/s | | | | | |
| | | | | | |

(E) none of these

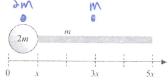
| A | work |
|---------------------|---|
| (B) | angular momentum . |
| | power $AP = \mathbf{m}FAt$ |
| | linear momentum |
| E | none of these |
| in | A rod rests on frictionless ice. Forces that are equal in magnitude and opposite direction are then simultaneously applied to its ends as shown. The quantity that zero is its: AP= FAT angular momentum total linear momentum kinetic energy rotational inertia |
| CO | A 2.0-kg stone is tied to a 0.50-m long string and swung around a circle at a nstant angular velocity of 12 rad/s. The net torque on the stone about the center the circle is: Constant newcity mounts no acceleration 12N·m 72N·m 140N·m |
| | A man, with his arms at his sides, is spinning on a light frictionless turntable. hen he extends his arms: his angular velocity increases his angular velocity remains the same his rotational inertia decreases his rotational kinetic energy increases his angular momentum remains the same A man, with his arms at his sides, is spinning on a light frictionless turntable. hen he extends his arms at his sides, is spinning on a light frictionless turntable. hen he extends his arms at his sides, is spinning on a light frictionless turntable. hen he extends his arms at his sides, is spinning on a light frictionless turntable. her he extends his arms at his sides, is spinning on a light frictionless turntable. her he extends his arms at his sides, is spinning on a light frictionless turntable. her he extends his arms at his sides, is spinning on a light frictionless turntable. her he extends his arms at his sides, is spinning on a light frictionless turntable. her her he extends his arms at his sides, is spinning on a light frictionless turntable. her her her her her her his arms at his sides, is spinning on a light frictionless turntable. her her her her her her his arms at his arms arms arms arms arms arms arms arm |
| 33 Fig A B | A machine part is made up of two pieces, with centers of gravity shown in the gure. Which point could the center of gravity of the entire part? A between the Other A. Center of gravity of piece 2 A Center of gravity of piece 2 Center of gravity of piece 1 C. Center of gravity of piece 1 |

29. The newton-second is a unit of:



39. A solid sphere of diameter x and mass 2m is fastened to a long thin rod of length 4x and mass m as shown. Where is the location of the center of mass of this system?

- A) X
- (B) 4x/3
- (c) 3x/2
- D 5x/3



$$\chi_{cg} = \frac{\lambda m(\frac{1}{2}x) + m(3x)}{\lambda m + m}$$

$$= \frac{mx + 3mx}{3m} = \frac{4mx}{3m} = \frac{4}{3}x$$